

1. (20 points) Short answer questions. No explanation of answers needed for this problem only. Be sure to explain your answers and show your work on all other problems!

- (a) True or False: If A , B , and X are invertible matrices such that $XA = B$, then $X = A^{-1}B$.

False. $X = BA^{-1}$

- (b) True or False: If A is a square matrix whose columns add up to the zero vector, then A is invertible.

False. this means the columns are L.D. so A has no inverse.

- (c) True or False: If A is an invertible matrix, then A and A^T have the same null space.

True. A invertible means $\text{null}(A) = \{0\}$ and A^T invertible means $\text{null}(A^T) = \{0\}$.

- (d) True or False: If A is a 3×5 matrix such that $(\text{row}(A))^\perp = \mathbb{R}^5$, then A must be the zero matrix.

True. $\mathbb{R}^5 = (\text{row}(A))^\perp = \text{ker}(A^T)$ ~~so A^T is invertible~~
 $= \text{null}(A) = \{0\}$ ~~so A is invertible~~ ~~so $A = 0$~~

- (e) True or False: If an $n \times n$ matrix has n distinct eigenvalues, then it must be diagonalizable.

True. main theorem about diagonalization

- (f) True or False: The transformation $T : \mathbb{R}^5 \rightarrow \mathbb{R}^5$ defined by $T(\vec{x}) = -\vec{x}$ is a linear transformation.

True. check properties.

- (g) True or false: The transformation $T : \mathbb{R}^4 \rightarrow \mathbb{R}^1$ defined by $T(\vec{x}) = \|\vec{x}\|$ is a linear transformation.

False. $T(-2\vec{x}) = \| -2\vec{x} \| = 2\| \vec{x} \| \neq -2T(\vec{x})$

- (h) If A is a 3×5 matrix, what are the possible values of $\text{nullity}(A)$?

rank + nullity = 3 so nullity = 0, 1, 2, 3

- (i) Let $\vec{a}_1, \vec{a}_2, \vec{a}_3$ be linearly independent vectors in \mathbb{R}^7 , and let $A = [\vec{a}_1 \vec{a}_2 \vec{a}_3]$. What are the possible values for the rank of A ?

rank $A = 3$ ($\vec{a}_1, \vec{a}_2, \vec{a}_3$ L.I.).

- (j) Let S be a subspace of \mathbb{R}^n , and let \vec{v} and \vec{u} be vectors in \mathbb{R}^n . If $\text{proj}_S \vec{v} = \vec{u}$, what is $\text{proj}_S \vec{u}$?

\vec{u} is in S so $\text{proj}_S \vec{u} = \vec{u}$.

2. (20=6+2+8+4 points) Let $A = \begin{bmatrix} -5 & -6 & 3 \\ 3 & 4 & -3 \\ 0 & 0 & -2 \end{bmatrix}$.

(a) Compute the characteristic polynomial of A .

$$\begin{aligned}\det(A - \lambda I) &= \det \begin{bmatrix} -5-\lambda & -6 & 3 \\ 3 & 4-\lambda & -3 \\ 0 & 0 & -2-\lambda \end{bmatrix} \\ &= (-2-\lambda)((-5-\lambda)(4-\lambda)+18) \\ &= (-2-\lambda)(\lambda+2)(\lambda-1)\end{aligned}$$

(b) Find all of the eigenvalues of A .

$$\text{eigenvalues: } \lambda = -2, 1 \leftarrow \begin{array}{l} \text{mult. 1} \\ \text{mult. 2} \end{array}$$

(c) Find a basis for each of the eigenspaces of A .

$$\lambda = -2: A + 2I = \begin{bmatrix} 3 & -6 & 3 \\ 3 & 6 & -3 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\text{eigenspace: } \left\{ s_1 \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + s_2 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}$$

$$\text{basis: } \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}$$

$$\lambda = 1: A - I = \begin{bmatrix} -6 & -6 & 3 \\ 3 & 3 & -3 \\ 0 & 0 & -3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\text{eigenspace: } \left\{ s \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \right\}, \text{ basis: } \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \right\}$$

(d) Is A diagonalizable? If yes, find P and D ; if not, explain why.

$$\text{Yes, } P = \begin{bmatrix} -2 & 1 & -1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}, D = \begin{bmatrix} -2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

3. (9=4+5 points) Let $\vec{x} = \begin{bmatrix} 3 \\ -4 \end{bmatrix}$ and $\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$. $\bar{u}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $\bar{u}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

(a) Find the coordinate vector $[\vec{x}]_{\mathcal{B}}$ of \vec{x} with respect to \mathcal{B} .

$$\bar{x}_{\mathcal{B}} = U^{-1} \vec{x}$$

$$\bar{x}_{\mathcal{B}} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ -4 \end{bmatrix} = \boxed{\begin{bmatrix} 7 \\ -4 \end{bmatrix}}_{\mathcal{B}}$$

$$U = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$$U^{-1} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

(b) Assume that \mathcal{C} is another basis for \mathbb{R}^2 , and that the change of basis matrix from \mathcal{C} to \mathcal{B} is $\begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$. Find the coordinate vector $[\vec{x}]_{\mathcal{C}}$ of \vec{x} with respect to \mathcal{C} .

This says $\bar{x}_{\mathcal{B}} = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \bar{x}_{\mathcal{C}}$

$$\text{so } \bar{x}_{\mathcal{C}} = (\begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix})^{-1} \bar{x}_{\mathcal{B}} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 7 \\ -4 \end{bmatrix} = \boxed{\begin{bmatrix} 7 \\ 3 \end{bmatrix}}_{\mathcal{C}}$$

4. (6 points) Find a basis for W^\perp if

$$W = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \\ 2 \end{bmatrix} \right\}. \quad \bar{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \bar{v}_2 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ 2 \end{bmatrix}$$

$$W^\perp = \{ \bar{u} \text{ such that } \bar{u} \cdot \bar{v}_1 = 0 \text{ and } \bar{u} \cdot \bar{v}_2 = 0 \}$$

$$\bar{u} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

$$\bar{u} \cdot \bar{v}_1 = x_1 + x_2 + x_3 + x_4 = 0$$

$$\bar{u} \cdot \bar{v}_2 = x_1 - x_2 + x_3 + 2x_4 = 0$$

$$\begin{aligned} W^\perp & : \begin{array}{c|c} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & 2 \end{array} \begin{array}{l} | 0 \\ | 0 \end{array} \rightarrow \begin{array}{c|c} 1 & 1 & 1 & 1 \\ 0 & -2 & 0 & 1 \end{array} \begin{array}{l} | 0 \\ | 0 \end{array} \\ & \rightarrow \begin{array}{c|c} 1 & 0 & 1 & 3/2 \\ 0 & 1 & 0 & -1/2 \end{array} \begin{array}{l} | 0 \\ | 0 \end{array} \Rightarrow x_3, x_4 \text{ free} \end{aligned}$$

$$W^\perp = \left\{ s_1 \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + s_2 \begin{bmatrix} -3/2 \\ 1/2 \\ 0 \\ 1 \end{bmatrix} \right\}$$

basis: $\left\{ \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -3/2 \\ 1/2 \\ 0 \\ 1 \end{bmatrix} \right\}$

5. (5 points) Find the coordinate vector $[\vec{v}]_B$ of $\vec{v} = \begin{bmatrix} 7 \\ -3 \\ 2 \end{bmatrix}$ with respect to orthogonal basis

$$B = \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} \right\} \text{ of } \mathbb{R}^3. \quad \bar{u}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \bar{u}_2 = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \bar{u}_3 = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}$$

orthogonal basis \Rightarrow

$$\vec{v} = c_1 \bar{u}_1 + c_2 \bar{u}_2 + c_3 \bar{u}_3,$$

$$c_1 = \frac{\vec{v} \cdot \bar{u}_1}{\|\bar{u}_1\|^2} = \frac{9}{2}$$

$$c_3 = \frac{\vec{v} \cdot \bar{u}_3}{\|\bar{u}_3\|^2} = -\frac{11}{6}$$

$$c_2 = \frac{\vec{v} \cdot \bar{u}_2}{\|\bar{u}_2\|^2} = \frac{2}{3}$$

$$[\vec{v}]_B = \begin{bmatrix} 9/2 \\ 2/3 \\ -11/6 \end{bmatrix}$$

6. (5 points) Compute $\det A^5$ if $A = PDP^{-1}$, where

$$P = \begin{bmatrix} 3 & 0 & 1 \\ 2 & 1 & 0 \\ 3 & -1 & -1 \end{bmatrix} \text{ and } D = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & -2 \end{bmatrix}.$$

$$\text{then } A^5 = (PDP^{-1})^5 = PD^5P^{-1}$$

$$\det(A^5) = \det(PD^5P^{-1}) = \det(D^5)$$

$$D^5 = \begin{bmatrix} 3^5 & 0 & 0 \\ 0 & 2^5 & 0 \\ 0 & 0 & (-2)^5 \end{bmatrix}$$

$$\det(D^5) = (3^5 \cdot 2^5 \cdot (-2)^5)$$

7. (5 points) Show that if λ is an eigenvalue of an $n \times n$ matrix C , then λ^3 is an eigenvalue of C^3 .

If λ is an eval of C ,

$$\det(C - \lambda I) = 0.$$

Want to show $\det(C^3 - \lambda^3 I) = 0$.

$$\text{But } C^3 - \lambda^3 I = (C - \lambda I)(C^2 + \lambda C + \lambda^2 I)$$

$$\text{so } \det(C^3 - \lambda^3 I) = \det(C - \lambda I) \det(C^2 + \lambda C + \lambda^2 I)$$

$$\text{so } \det(C^3 - \lambda^3 I) = 0 \text{ so } \lambda^3 \text{ is an eval. of } C^3.$$

8. (5 points) Explain why a square matrix that has two equal rows, must have 0 as one of its eigenvalues.

If a square matrix A has two equal rows, $\det(A) = 0$.

$$\text{But, } 0 = \det(A) = \det(A - 0 \cdot I)$$

so 0 is an eval. of A.

9. (5 points) Let A and B be 3×4 matrices. Show that $W = \{\vec{x} \in \mathbb{R}^4 : A\vec{x} = B\vec{x}\}$ is a subspace of \mathbb{R}^4 .

(1) $\vec{0}$ in W ?

$$\text{Yes: } A \cdot \vec{0} = \vec{0} = B \cdot \vec{0}$$

\uparrow
to be in W ,
must satisfy
this condition.

(2) If \vec{u}, \vec{v} in W , is $\vec{u} + \vec{v}$?

Yes: if $A\vec{u} = B\vec{u}$ and

$$A\vec{v} = B\vec{v},$$

then

$$A\vec{u} + A\vec{v} = B\vec{u} + B\vec{v}$$

$$A(\vec{u} + \vec{v}) = B(\vec{u} + \vec{v})$$

so $\vec{u} + \vec{v}$ is in W

(3). If \vec{u} in W , is $r\vec{u}$?

Yes: if $A\vec{u} = B\vec{u}$,

$$\text{then } rA\vec{u} = rB\vec{u}$$

$$A(r\vec{u}) = B(r\vec{u})$$

so $r\vec{u}$ is in W .